

MGC® R3



KONGSBERG



GYRO COMPASS AND INS

A new family of products with motion sensing and gyro compass functionality is introduced. The first product in this family is the MGC R3 which includes three Ring Laser Gyros and three linear accelerometers.

Typical applications

The MGC R3 product is a fully inertial navigation system (INS). It can output heading, roll, pitch, heave and position. Acceleration and velocity of linear motions, as well as angular rates, are output from the unit. The MGC R3 product outputs both processed and raw (gyro and accelerometer) sensor data.

The MGC R3 product can be used as a stand-alone unit or as an IMU in other systems. The product is designed for high precision maritime applications such as offshore operations and seabed mapping.

The product includes integrated navigation algorithms with input from a GNSS receiver for output of aided position and heading data. The proven PFreeHeave® algorithms are part of the navigation algorithms that enable down to 2 cm accuracy in delayed heave output and 5 cm accuracy in real-time heave output. The linear position and velocity measurements can be output in up to four different points on the vessel.

The mounting bracket has been specially designed to enable easy alignment to the vessel axis or the axes of the system on which the unit shall measure the motion. This will ensure that the user gets precise measurements from the unit when it is installed.

Function

The MGC can operate in Gyrocompass mode and Integrated Navigation mode. In the Gyrocompass mode only, input of speed is required. In this mode the product

will output heading, roll, pitch and heave accurately. In the Integrated Navigation mode, input of speed, position and PPS from a GNSS receiver is required (VTG, GGA, ZDA). In this mode the product will output heading, roll, pitch, heave and position.

The unit is delivered with Windows based configuration and data presentation software, the MRC+. In this software vector arms from where the MGC is mounted to the center of gravity (CG) and two individually configurable monitoring points (MPs) can be defined. The heave measurements can be output in four different locations (the MGC itself, CG, MPI and MP2) simultaneously on serial lines or Ethernet ports. A typical measurement point is the echo sounder transducer head.

Variables output

The MGC outputs heading, roll and pitch and corresponding angular rate vectors. The unit outputs relative (dynamic) heave position, velocity and acceleration. In the Integrated Navigation mode it also outputs position in north and east direction in addition to height above the ellipsoid.

Digital I/O protocols

MGC data is available through both Ethernet interface and serial lines enabling easy distribution of data to multiple users on board the vessel. Output protocols for commonly used survey equipment are available on two individually configurable serial lines and Ethernet/UDP.

FEATURES

- 0.01° roll and pitch accuracy
- 0.08° secant latitude heading accuracy
- Includes INS capability
- Outputs on RS-232, RS-422 and Ethernet
- High output data rate (200 Hz)
- Precise heave at long wave periods by use of PFreeHeave® algorithms
- Lever arm compensation to two individually configurable monitoring points
- Small size and low power consumption
- Each MGC delivered with a Calibration Certificate
- Selectable communication protocols in the Windows based configuration software



TECHNICAL SPECIFICATIONS

MGC R3

ORIENTATION OUTPUT

Angular orientation range	±180°
Resolution in all axes	0.001°
Accuracy roll, pitch	0.01° RMS
Accuracy heading	0.08° RMS sec.lat
Accuracy heading (GNSS aided)	0.04° RMS sec.lat
Heading settling time (typical)	17 min from start-up

GYRO OUTPUT

Angular rate range	±149°/s
Angular rate noise	0.010°/s RMS
Bias stability (absolute bias)	0.008°/h RMS
Angle Random Walk	0.008°/√h RMS
Scale factor error	0.001 % RMS

ACCELERATION OUTPUT

Acceleration range (all axes)	±30 m/s ²
Bias stability (absolute bias)	80 µg RMS
Acceleration noise	0.0002 m/s ² RMS
Velocity Random Walk	3.3 µg/√Hz
Scale factor error	0.008% RMS

HEAVE OUTPUT

Output range	±50 m, adjustable
Periods (real-time)	0 to 25 s
Periods (delayed)	0 to 50 s
Heave accuracy (real-time)	5 cm or 5% whichever is highest
Heave accuracy (delayed)	2 cm or 2% whichever is highest

POSITION OUTPUT

Free inertial	5 nm/h
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ELECTRICAL

Voltage input	24 V DC nominal (18 to 32 V DC)
Power consumption	Max 12 W (typical 11 W)
Serial ports:	
Com1	Bidirectional RS-422
Com2	Bidirectional RS-422 from junction box, user configurable RS-232, RS-422

Com3 & Com4

Analog channels (junction box)

Ethernet output ports
Ethernet UPD/IP
Digital output variables

Data output rate (max)
Timing

INPUT FORMATS

NMEA 0183, incl. GGA, VBW, VTG, ZDA or MRU Normal format

OUTPUT FORMATS

- MRU normal
- NMEA 0183 proprietary
- Atlas Fansweep
- Seapath binary 23, 25, 26
- KM binary
- RDI ADCP
- NMEA GGA, GLL, HDT, THS, ROT, VTG, GST, VER, HCR

OTHER DATA

MTBF (computed) 50000 h
MTBF (service history based) 100000 h
Material Anodised aluminium
Connector (MIL. spec.) Souriau 851-36RG 16-26S50

WEIGHT AND DIMENSIONS

Weight 8.1 kg
Dimensions (HxLxW) 188.9 x 189.5 x 189.5 mm

ENVIRONMENTAL SPECIFICATIONS

Operational temperature range -15 °C to +55 °C
Storage temperature range -25 °C to +70 °C
Enclosure protection IP66
Vibration IEC 60945/EN 60945

ELECTROMAGNETIC COMPATIBILITY

Compliance to EMC, immunity/emission IEC 60945/EN 60945

Specifications subject to change without any further notice.

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