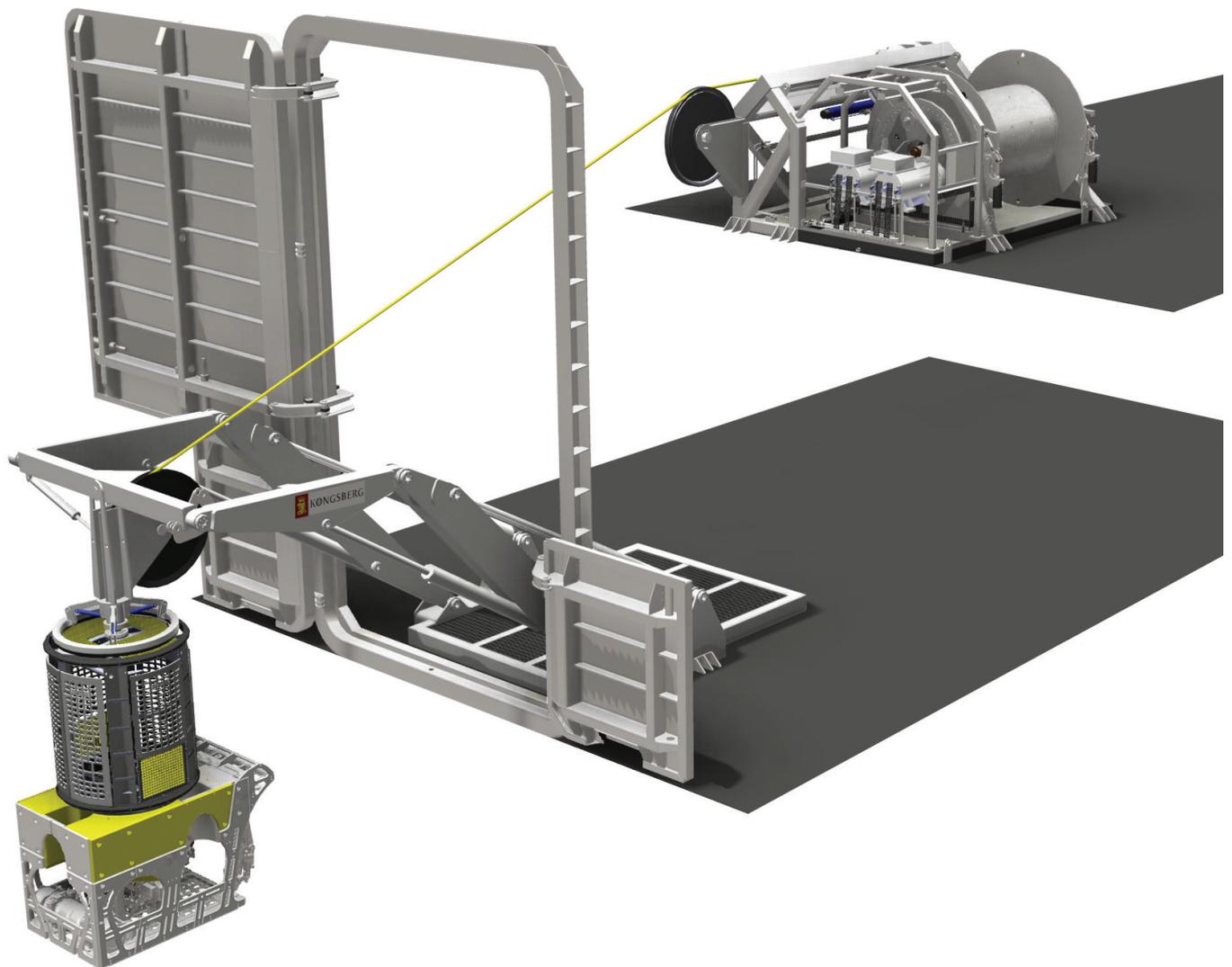


Electrical LARS for WROV

E-LARS



KONGSBERG



Electrical LARS for WROV, using permanent magnet motors

Evotec Launch and Recovery System (E-LARS) is designed to handle work ROVs with or without TMS to depths below 4000 m. The system is designed in close cooperation with end users, umbilical manufacturers, ROV suppliers and ship designers.

Personnel safety, gentle handling of umbilical and ROV and easy maintenance form the basis for the complete design of both the advanced control system and the mechanical design of the E-LARS. This is to ensure the best uptime for the complete ROV system.

Electric Umbilical winch

The umbilical winch is equipped with two frequency controlled permanent magnet high torque motors. Two fail safe disc brakes are mounted on the drum for brake redundancy. The large sheave D:d ratio on the spooling device ensures correct spooling and best life time for the umbilical.

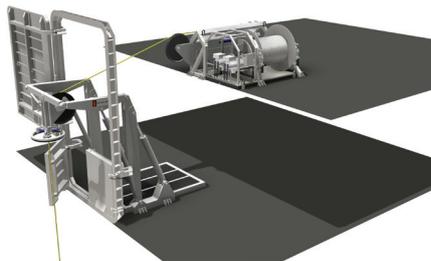
A-frame:

The A-frame is equipped with two pivot points to achieve a good outreach and at the same time have as low unguided lifting height as possible. This good manoeuvrability enables the A-frame to operate 5.2 m packages in hangars with only 8.0 m hangar heights. The A-frame design also makes it possible to close the lower hangar port during operations if needed.

Mool pool system:

The moon pool system is designed for safe and effective launch and

recovery of the ROV/TMS through the moon pool in a vessel. The ROV/TMS is lifted by a lifting wire and a dedicated cursor winch through the splash zone, this to ensure the best possible life time for the umbilical. Good functionality and low maintenance costs forms the basis through the complete moon pool handling unit design.



A-frame

Lower hangar door can be closed during operation

General:

| | |
|--------------------------|---|
| Max ROV/TMS weight (dry) | 20.0/12.0 Te (deployed load/docking head lock) |
| Max operation depth | 4000 + m |
| Max power consumption | 650 kW |
| Certification | DnV Standard for Certification No 2.22 - Lifting Appliances |

Umbilical Winch:

| | |
|----------------------|-----------------------------------|
| SWL | 20.0/12.0 Te (inner/outer layer) |
| Max braking capacity | 36.0/22.0 Te (inner/outer layer) |
| Max hoisting speed | 2.5 m/s (all layers) |
| Max acceleration | 2.0 m/s ² (all layers) |

A-frame:

| | |
|------------------------|--|
| SWL | 20.0/12.0 Te (deployed load/docking head lock) |
| Docking head functions | - Fail safe lock - Rotation - Tilt - in/out - Tilt - left/right - Damping |
| Max package height | Depending on package and hangar design > 5.2 m (8.0 m hangar height) > 6.0 m (9.0 m hangar height) |

Moon pool handling unit:

| | |
|--|-------------------------------------|
| SWL | 20.0/12.0 Te (deployed/cursor load) |
| Max launch / recovery speed (in moon pool) | 1.0 m/s |

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